

Towards modelling and Verification of Concurrent Ada programs using Petri Nets

A. Burns
A.J. Wellings
F.P. Burns
A.M. Koelmans
M. Koutny
A. Romanovski
A.V. Yakovlev

Atomic Actions

- Structuring of complex concurrent systems
- Several action participants
- Synchronous or asynchronous entry
- Synchronous exit
- No flow across border during action
- System layering
- Complexity hiding

Error Recovery

- Indivisible units of execution
- All-or-nothing semantics
- Tolerance of software faults
- Backward error recovery
 - Restore previous state
- Forward error recovery
 - Exception handling

ADA features

- Packages
- Types
- Asynchronous transfer of control
- Protected types
- Requeue
- Exceptions
- Controlled types

Problems with ADA

- Model is very complex
- Even small examples have many states
- Need confidence in correctness
- Use Petri Nets to model concurrency
- Analyse using PN tools
 - PEP
 - INA
 - Design/CPN

ADA example

```
package simple_action is
  procedure T1(params : param); -- from Task 1
  procedure T2(params : param); -- from Task 2
  procedure T3(params : param); -- from Task 3
end simple_action;
```

```

with Ada.Exceptions; use Ada.Exceptions;
package body action is

type Vote_T is (Commit, Aborted);
protected controller is
  entry Wait_Abort(E: out Exception_Id);
  entry Done;
  entry Cleanup (Vote : Vote_t; Result : out Vote_t);
  procedure Signal_Abort(E: Exception_Id);
private
  entry Wait_Cleanup(Vote : Vote_t; Result : out Vote_t);
  Killed : boolean := False;
  Releasing_cleanup : Boolean := False;
  Releasing_Done : Boolean := False;
  Reason : Exception_Id;
  Final_Result : Vote_t := Commit;
  informed : integer := 0;
end controller;

```

```

protected body controller is
  entry Wait_Abort(E: out Exception_id) when killed is
  begin
    E := Reason;
    informed := informed + 1;
    if informed = 3 then
      Killed := False;
      informed := 0;
    end if;
  end Wait_Abort;

```

```

entry Done when Done'Count = 3 or Releasing_Done is
begin
  if Done'Count > 0 then
    Releasing_Done := True;
  else
    Releasing_Done := False;
  end if;
end done;

entry Cleanup (Vote: Vote_t;
  Result: out Vote_t) when True is
begin
  if Vote = aborted then
    Final_result := aborted;
  end if;
  requeue Wait_Cleanup with abort;
end Cleanup;

```

```

procedure Signal_Abort(E: Exception_id) is
begin
  killed := TRue;
  reason := E;
end Signal_Abort;

entry Wait_Cleanup (Vote : Vote_t; Result: out Vote_t)
  when Wait_Cleanup'Count = 3 or Releasing_Cleanup is
begin
  Result := Final_Result;
  if Wait_Cleanup'Count > 0 then
    Releasing_Cleanup := True;
  else
    Releasing_Cleanup := False;
    Final_Result := Commit;
  end if;
end Wait_Cleanup;
end controller;

```

```

procedure T1(params: param) is
  X : Exception_ID;
  Decision : Vote_t;
begin
  select
    Controller.Wait_Abort(X);
    raise_exception(X);
  then abort
    begin
      -- code to implement atomic action
      Controller.Done; --signal completion
    exception
      when E: others =>
        Controller.Signal_Abort (Exception_Identity(E));
    end;
  end select;

```

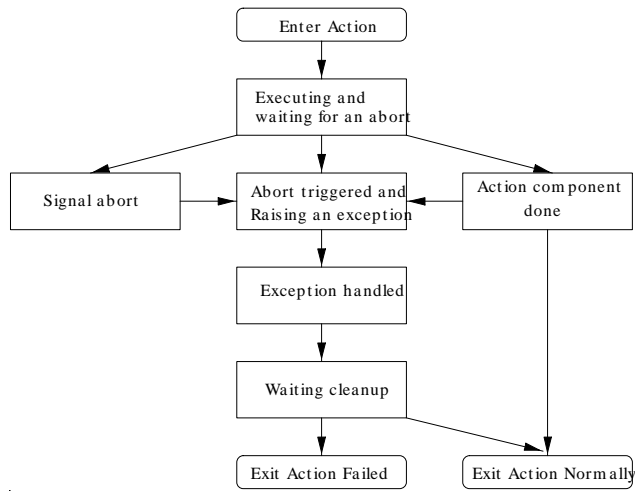
```

exception
  -- if any exception is raised during the action
  -- all tasks must participate in the recovery
  when E: others =>
    -- Exception_Identity(E) has been raised in all tasks
    -- handle exception
    if handled_ok then
      Controller.Cleanup(Commit, Decision);
    else
      Controller.Cleanup(Aborted, Decision);
    end if;
    if decision = aborted then
      raise atomic_action_failure;
    end if;
  end T1;

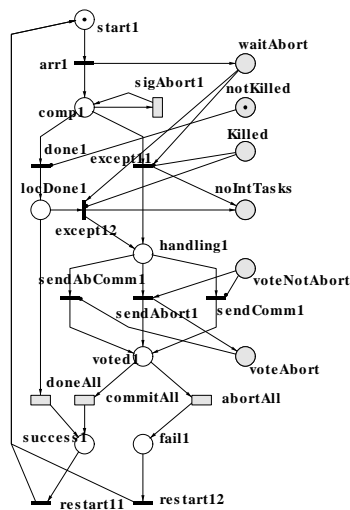
  -- similar for T2 and T3
end action;

```

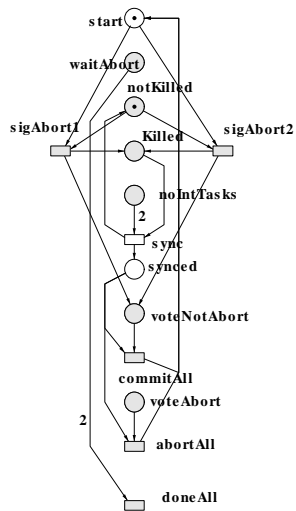
State diagram



Task Model



Controller model



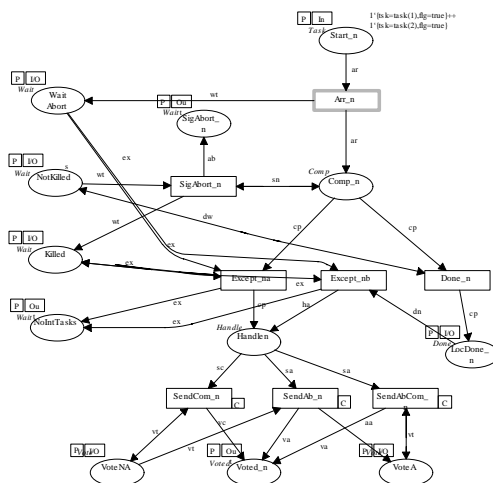
Verification with PEP

success1,fail2
-- results in <NO>

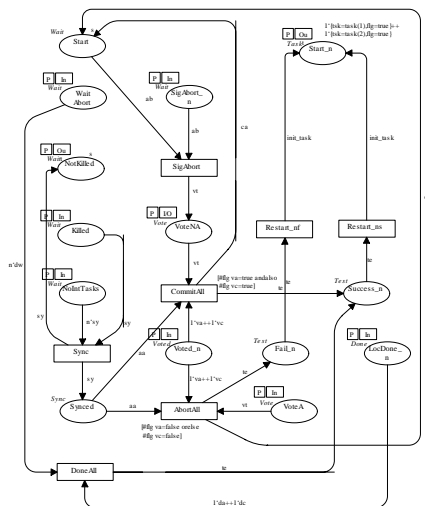
Success1,success2
-- results in <YES>

Fail1,fail2
-- results in <YES>

Task model



Control model



Design/CPN: Statistics

Occurrence Graph	Sec Graph
Nodes: 63	Nodes: 13
Arcs: 114	Arcs: 14
Secs: 0	Secs: 0
Status: Full	

Design/CPN: Boundedness

Best Integers Bounds	Upper	Lower
ControlFail_n 1	1	0
ControlKilled 1	1	0
ControlLocDone_n 1	2	0

Design/CPN: liveness

Dead Markings: None	Control'AbortAll 1	Fair
Live Transitions Instances:	Control'CommitAll 1	Fair
	Control'DoneAll 1	Fair
Control'AbortAll 1	Control'Restart_nf 1	Fair
Control'CommitAll 1	Control'Restart_ns 1	Fair
Control'Restart_nf 1	Control'SigAbort 1	Fair
Control'Restart_ns 1	Control'Sync 1	Fair
Control'SigAbort 1	Tasks'Arr_n 1	Impartial
Control'Sync 1	Tasks'Done_n 1	Just

Conclusions

- Modelling and verification possible
- Improve confidence in correctness
- Hand translation only
- Need automated extraction
- No real-time issues yet

