

EEE2002 – Supplementary material

Transient Characteristics

A system has the following tf:

$$\frac{C(s)}{R(s)} = \frac{1}{s^2 + 3s + 5}$$

Note: The num is not w_n^2 but the w_n and z will be found from the den

1. Find the order of the system.
2. Find the characteristic equation of the system.
3. Find the poles of the system (Use the command roots).
4. What kind of response do you expect from that system just by looking at the pole location?
5. Find the damping factor and the natural frequency of the system by the previous pole location.
6. Find analytically its damping factor and natural frequency.
7. By using Matlab crosscheck your answer.
8. By using the appropriate formulas find the maximum overshoot (Mp), the settling time (2%) and the peak time of the system.
9. By using Matlab find the step response of the system and by using the appropriate tools (in the figure GUI) crosscheck your answer.

Solution:

1.

The order of the system is the order of the denominator: 2.

2.

The CE is the eqn that is created by the denominator of the TF, i.e. $s^2 + 3s + 5 = 0$

3.

The poles can be found by solving the CE:

```
>> roots([1 3 5])
```

```
ans =
```

```

-1.5000 + 1.6583i
-1.5000 - 1.6583i
Or
>> num=1; den=[1 3 5]; g=tf(num,den), [p,z]=pzmap(g)

```

Transfer function:

```

      1
-----
s^2 + 3 s + 5

```

p =

```

-1.5000 + 1.6583i
-1.5000 - 1.6583i

```

z =

Empty matrix: 0-by-1

4.

Since the system has two complex poles the system must be oscillatory.

5.

The angle of a complex pole is $\tan^{-1}(\text{imaginary part} / \text{real part})$, i.e.

```
>> theta=atan(abs(imag(p(1)))/abs(real(p(1)))), cos(theta)
```

theta =

```
0.8355
```

ans =

```
0.6708
```

```
>> zwn=abs(real(p(1))); wn=zwn/z
```

wn =

```
2.2361
```

6.

The classical form of the CE is: $s^2 + 2\zeta\omega_n s + \omega_n^2 = 0$ and our CE is $s^2 + 3s + 5 = 0$. Hence by equating the relevant coefficients: $2\zeta\omega_n = 3$, $\omega_n^2 = 5$ so $\omega_n = 2.23\dots$, $\zeta = \frac{3}{2\omega_n} = 0.67$

7.

```
>> [wn, z]=damp(g)
```

```
wn =
```

```
2.2361  
2.2361
```

```
z =
```

```
0.6708  
0.6708
```

8.

The overshoot is given by $M_p = e^{-\left(\frac{\zeta}{\sqrt{1-\zeta^2}}\right)\pi}$, hence:

```
>> Mp=100*exp(-z*pi/sqrt(1-z^2))
```

```
Mp =
```

```
5.8697
```

So the overshoot is 5.8%.

The settling time is $ts_{2\%} = \frac{4}{\zeta\omega_n}$, hence:

```
>> wn=wn(1); z=z(1); % Previously I used the command [wn,z]=damp(g)
```

```
>> ts=4/z/wn
```

```
ts =
```

```
2.6699
```

So the system will enter into an envelope of +/-2% of the final value after 2.7s.

The peak time is $tp = \pi / \omega_d$, hence:

```
>> wd=wn*sqrt(1-z^2), tp=pi/wd
```

```
wd =
```

```
1.6600
```

```
tp =
```

```
1.8926
```

Hence the system will reach the first (and max) overshoot (of 5.8%) after 1.9 s.

9.

```
>> num=1; den=[1 3 5]; g=tf(num,den); step(g)
```



