

Revision

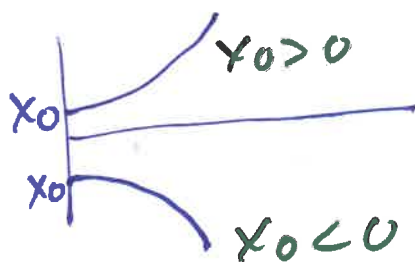
(5)

$$\dot{X} + kX = u \rightarrow$$

$$X = \underbrace{e^{-kt} \cdot X_0}_{\text{Trans.}} + \underbrace{e^{-kt} \int_0^t e^{kt_1} u(t_1) dt_1}_{\text{input}}$$

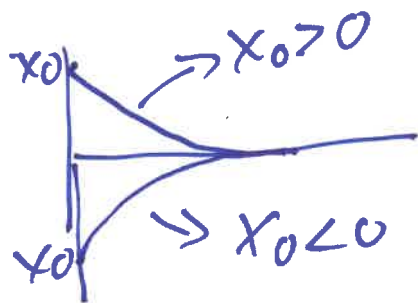
• $u=0$ $X = e^{-kt} \cdot X_0$

☑ $k < 0$



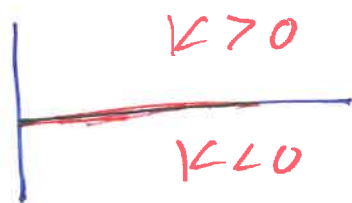
unstable

☑ $k > 0$



stable

if $X_0 = 0$



$k=0$

$$\dot{X} = 5$$

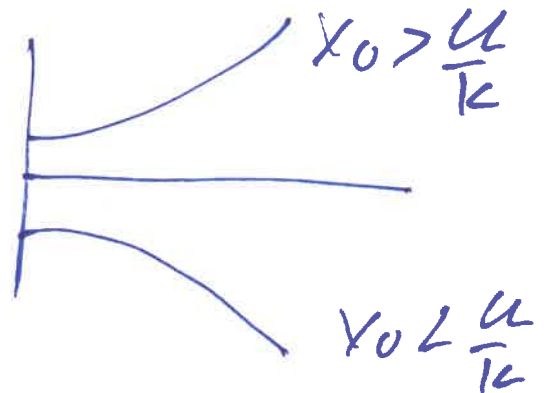
$$\int \dot{X} = \int 5 dt \Rightarrow X = 5 \cdot t + C$$

$u \neq 0$ but const.

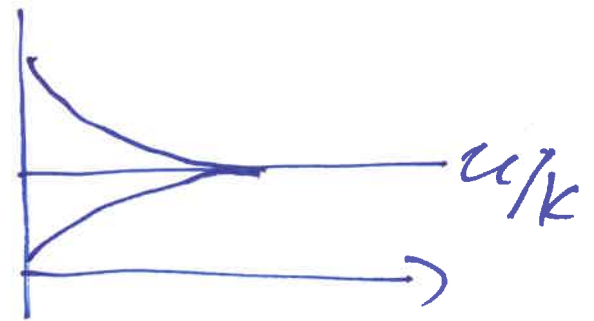
(6)

$$x = e^{-kt} \cdot x_0 + \frac{u}{k} (1 - e^{-kt})$$

• $k < 0$ unstable



• $k > 0$ stable



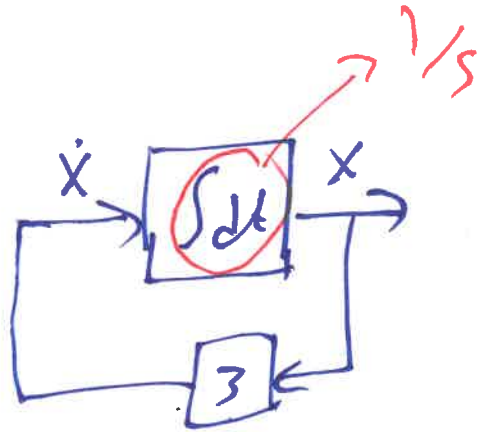
if $x_0 = \frac{u}{k}$

$$x = e^{-kt} \cdot \frac{u}{k} + \frac{u}{k} - \frac{u}{k} e^{-kt} = \frac{u}{k}$$

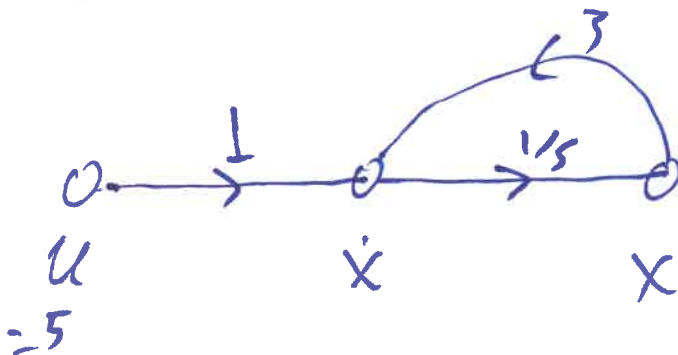
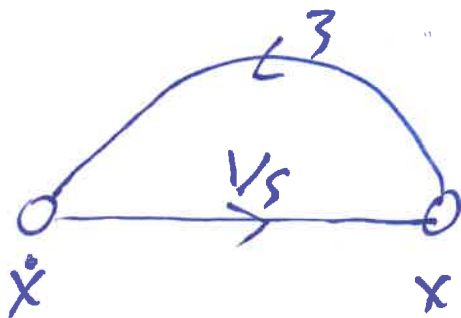
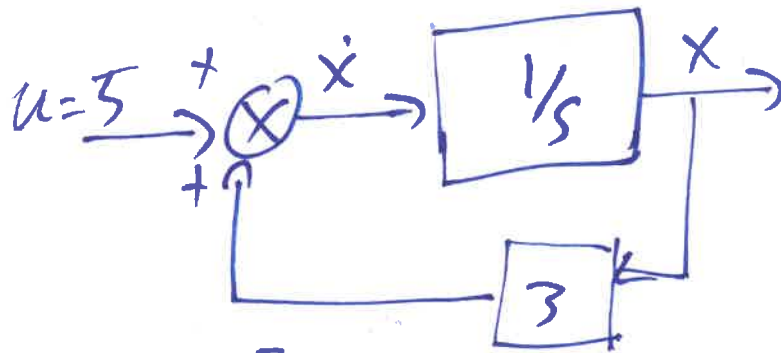
⑦

- Isolate the highest t. der.
- place as many int. as the order of O.D.
- Create the highest T.I).

$$\dot{X} = 3X$$



$$\dot{X} = 3X + 5$$



$$\ddot{x} + A\dot{x} + Bx = u$$

$$\downarrow u=0$$

$$\ddot{x} + A\dot{x} + Bx = 0$$

$$\downarrow \text{assume}$$

$$x = e^{rt}$$

$$\dot{x} = r e^{rt}$$

$$\ddot{x} = r^2 e^{rt}$$

$$r^2 e^{rt} + A r e^{rt} + B e^{rt} = 0$$

$$r^2 + A r + B = 0$$

$$r_{1,2} = \frac{-A \pm \sqrt{D}}{2}$$

$$D = A^2 - 4 \cdot B$$

$$\bullet D > 0 \Rightarrow r_1 \neq r_2 \in \mathbb{R}$$

$$\bullet D < 0 \Rightarrow r_1 = \bar{r}_2 \in \mathbb{C}$$

$$\bullet D = 0 \Rightarrow r_1 = r_2 = -\frac{A}{2}$$

$$\begin{aligned} \ddot{x} + \kappa x &= 0 \\ x &= e^{rt} \cdot C \end{aligned}$$

⑧

$$\ddot{x} - 2\dot{x} - 3x = 0 \quad \rightarrow \text{a soln, } \textcircled{9}$$

$$x_1 = e^{3t}$$

$$\dot{x}_1 = 3e^{3t}$$

$$\ddot{x}_1 = 9e^{3t}$$

$$9) \quad e^{3t} - 2 \cdot 3 \cdot e^{3t} - 3e^{3t} = 0$$

$$0 = 0$$

$$x_2 = 10 \cdot x_1 \rightarrow \text{a soln to ODE}$$

So if x_1 is a soln, then $k \cdot x_1$ is also a soln.

$$x_3 = e^{-t} \rightarrow \text{Another soln.}$$

$$\text{is } x_4 = x_1 + 2x_2 \quad \text{a soln} \quad \left. \vphantom{x_4 = x_1 + 2x_2} \right\} x_4 \text{ is a soln.}$$

$$\dot{x}_4 = \dots$$

$$\ddot{x}_4 = \dots$$

So if x_1, x_2 are soln \Rightarrow
L.C. of x_1, x_2 is also a soln.

$$y = C_1 \cdot x_1 + C_2 \cdot x_2$$