

# Root locus

The given TFs are:

$$G_{p1}(s) = \frac{1}{s(s+1)(s+2)}, G_{p2}(s) = \frac{1}{(s+0.8+3j)(s+0.8-3j)}$$

```
>> Gp1=tf(1,poly([0 -1 -2]))
```

Transfer function:

$$\frac{1}{s^3 + 3s^2 + 2s}$$

```
>> Gp2=tf(1,poly([-0.8-3*i -0.8+3*i]))
```

Transfer function:

$$\frac{1}{s^2 + 1.6s + 9.64}$$

```
>> G=Gp1*Gp2
```

Transfer function:

$$\frac{1}{s^5 + 4.6s^4 + 16.44s^3 + 32.12s^2 + 19.28s}$$

Using Matlab:

```
>> rlocus(G)
```

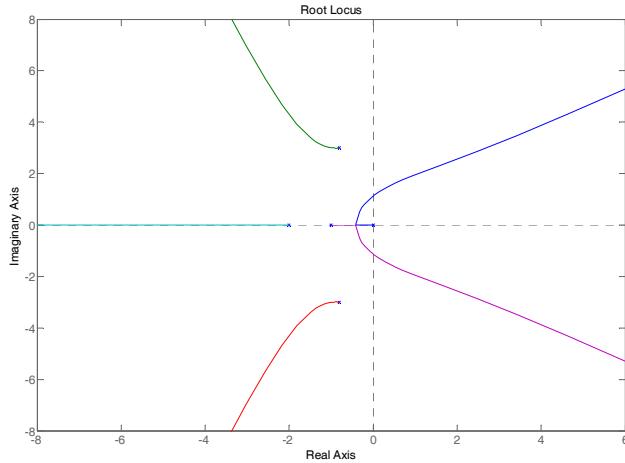


Figure 1 Root locus produced using rlocus().

The graphical method:

The open loops poles (there are no zeros) are obviously 0, -1, -2 from the 1<sup>st</sup> TF and  $-0.8 \pm 3j$  from the 2<sup>nd</sup> TF but it can also be found using Matlab:

```
>> [p, z] = pzmap(G)
p =
0
-0.80000000000000 + 3.00000000000000i
-0.80000000000000 - 3.00000000000000i
-2.00000000000001
-1.00000000000000
z =
Empty matrix: 0-by-1
```

Note: The steps shown here are at a different sequence than those presented in your handout (chapter 4, last page).

**Step 1:** Draw the OL poles and zeros:

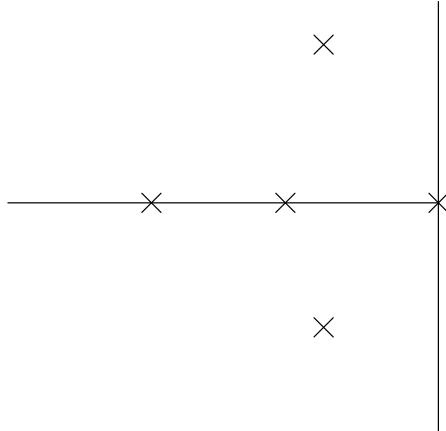


Figure 2 OL poles and zeros

**Step 2:** Determine which parts of the real axis belong to the RL:

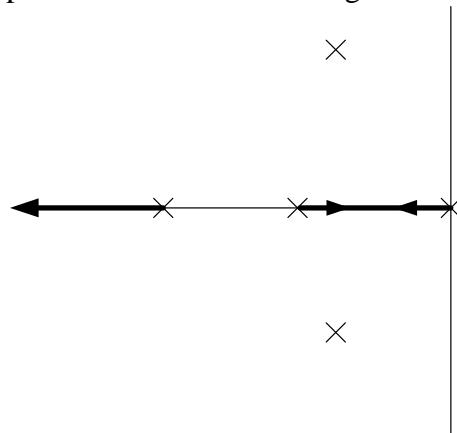


Figure 3 Real axis part

**Step 3:** The Break in/out points can be found from  $\frac{dk}{ds} = 0$  where  $k(s)$  is found using the CL CE:  $k = -s(s+1)(s+2)(s+0.8+3j)(s+0.8-3j)$

It will be easier if we first do the multiplication. This product is already calculated from:

```
>> G
```

Transfer function:

$$\frac{1}{s^5 + 4.6 s^4 + 16.44 s^3 + 32.12 s^2 + 19.28 s}$$

To isolate the OL denominator:

```
>> [n, d]=tfdata(G, 'v')
n =
    0     0     0     0     0     1
d =
    Columns 1 through 4
    1.00000000000000  4.60000000000000  16.44000000000000
32.12000000000001
    Columns 5 through 6
    19.28000000000000          0
```

To speed up the calculations (for our system) we have that k=-OL Denominator and hence:

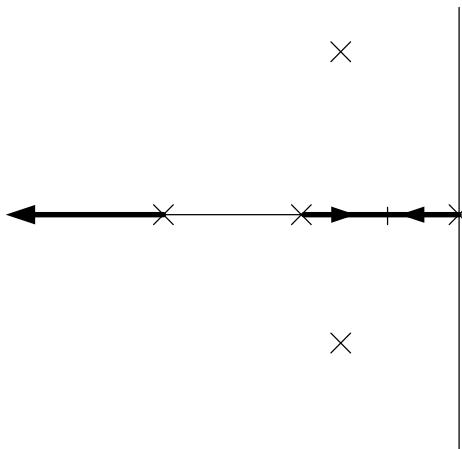
```
>> dd=[5*d(1) 4*d(2) 3*d(3) 2*d(4) d(5)]
dd =
    Columns 1 through 4
    5.00000000000000  18.40000000000000  49.32000000000000
64.24000000000001
    Column 5
    19.28000000000000
```

Note: Be very careful when you use the above trick!!!

The solution of  $\frac{dk}{ds} = 0$ :

```
>> roots(dd)
ans =
-0.83563600935911 + 2.26917322324496i
-0.83563600935911 - 2.26917322324496i
-1.59539068314996
-0.41333729813182
```

Hence the accepted solution (break out point) is the last one as the -1.59 is a point on the real that is not in the RL (use your mouse pointer on the Matlab figure to crosscheck your answer).



**Figure 4 Break out point**

**Step 4:** There are  $n_p - n_z = 5$  asymptotes and the point of intersection with the real axis:

$$s = -\frac{\sum_{i=1}^{n_p} p_i - \sum_{i=1}^{n_z} z_i}{n_p - n_z}$$

The poles are:

```
>> pj=-p
pj =
      0
0.800000000000000 - 3.00000000000000i
0.800000000000000 + 3.00000000000000i
2.000000000000001
1.000000000000000
```

And hence:

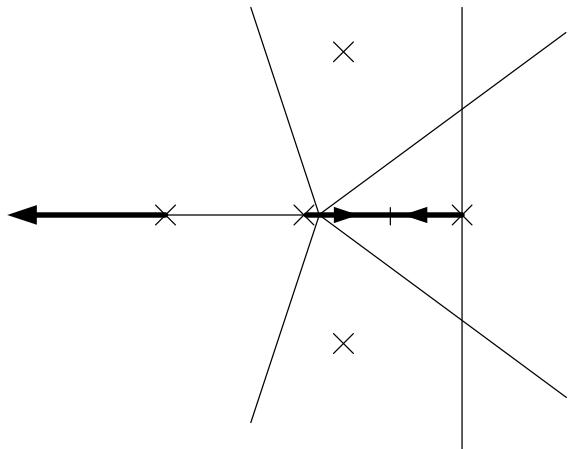
```
>> sum(pj)/5
ans =
0.920000000000000
```

Hence  $s = -0.92$

The angles of the asymptotes with the real axis are:

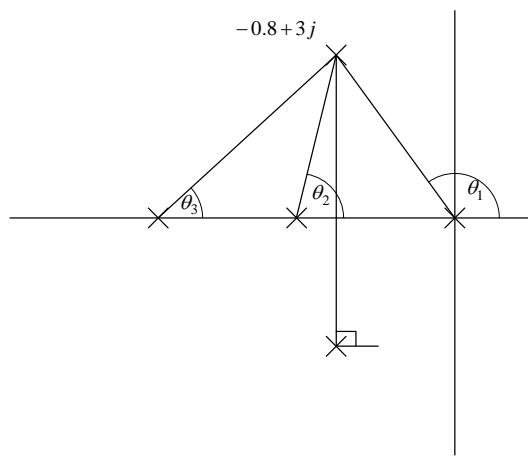
# asymptote	Angle
1	$180^\circ / 5 = 36^\circ$
2	$3 \times 180^\circ / 5 = 108^\circ$
3	$5 \times 180^\circ / 5 = 180^\circ$
4	$7 \times 180^\circ / 5 = 252^\circ$ or $-108^\circ$
5	$9 \times 180^\circ / 5 = 324^\circ$ or $-36^\circ$

The last 2 can also be found using the symmetry of the RL.



**Figure 5 Asymptotes**

**Step 5:** The angle of departure from the complex poles is found using the following drawing:



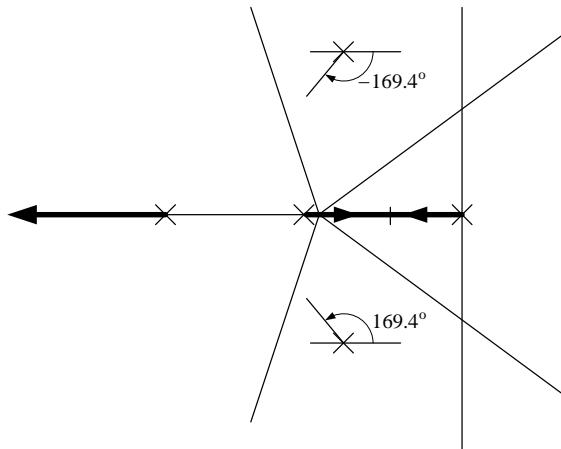
**Figure 6 Calculation of departure angle**

$$\theta_3 = \tan^{-1}\left(\frac{3}{1.2}\right) = 68.2^\circ$$

$$\theta_2 = \tan^{-1}\left(\frac{3}{0.2}\right) = 86.2^\circ$$

$$\tan^{-1}\left(\frac{3}{0.8}\right) = 75^\circ \Rightarrow \theta_1 = 180^\circ - 75^\circ = 105^\circ$$

So the angle of departure is  $180^\circ - 68.2^\circ - 86.2^\circ - 105^\circ - 90^\circ = -169.4^\circ$



**Figure 7 Angle of departure**

**Step 6:** The last point is the point of intersection with the imaginary axis. To do that we place at the CL CE  $s=j\omega$ :

$$\begin{aligned} s^5 + 4.6s^4 + 16.44s^3 + 32.12s^2 + 19.28s + k = 0 &\Leftrightarrow \\ j\omega^5 + 4.6\omega^4 - 16.44j\omega^3 - 32.12\omega^2 + 19.28j\omega + k = 0 &\Rightarrow \\ \left\{ \begin{array}{l} \omega^5 - 16.44\omega^3 + 19.28\omega = 0 \\ 4.6\omega^4 - 32.12\omega^2 + k \end{array} \right\} &\Rightarrow \\ \left\{ \begin{array}{l} \omega^4 - 16.44\omega^2 + 19.28 = 0 \\ 4.6\omega^4 - 32.12\omega^2 + k \end{array} \right\} \end{aligned}$$

```
>> roots([1 0 -16.44 0 19.28])
ans =
    3.89473818599817
   -3.89473818599818
    1.12739277207531
   -1.12739277207531
```

To find the accepted value:

```
>> w=3.89473818599817; k=-4.6*w^4+32.12*w^2
k =
-5.712235468221927e+002
>> w=1.12739277207531; k=-4.6*w^4+32.12*w^2
k =
33.39378682219768
```

Hence the accepted value is 1.12739277207531 and hence the gain is 33.4

Now we have all that we need to sketch the root locus:

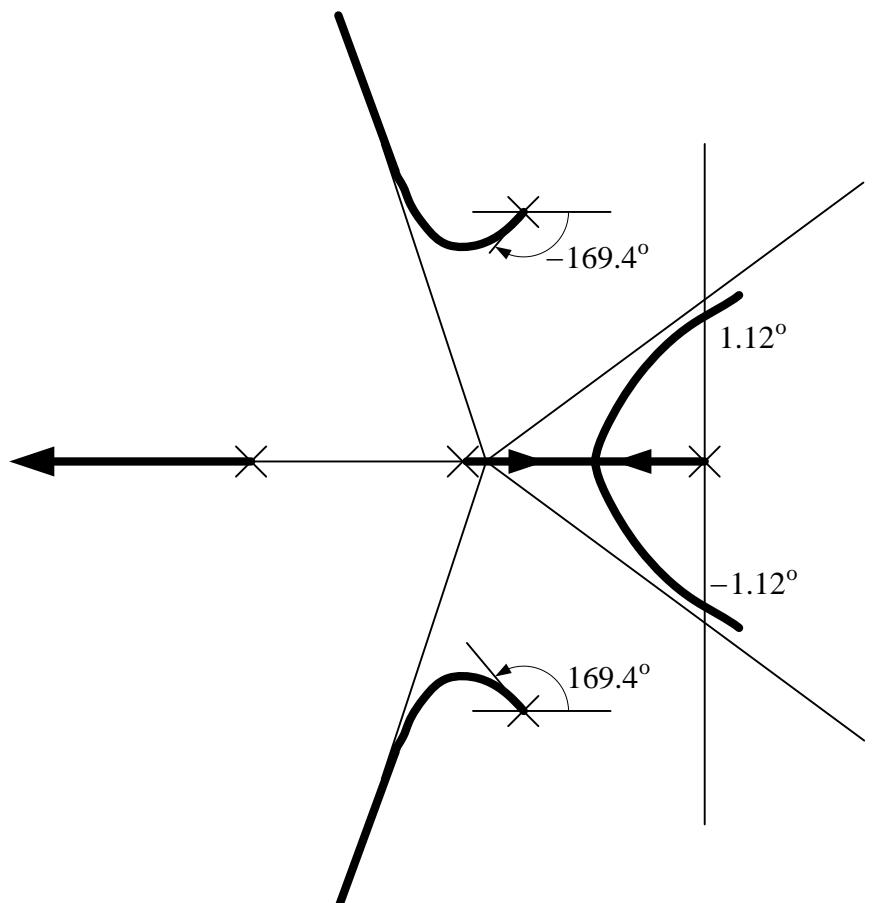


Figure 8

The given TFs are:

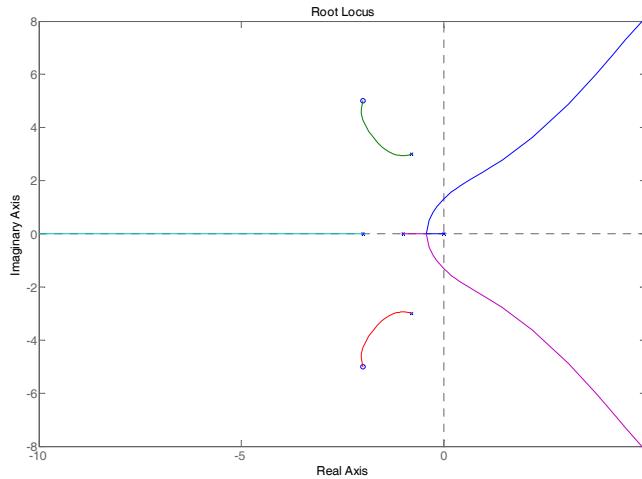
$$G_{p1}(s) = \frac{1}{s(s+1)(s+2)}, G_{p2}(s) = \frac{(s+2+5j)(s+2-5j)}{(s+0.8+3j)(s+0.8-3j)}$$

Note: This is a difficult one

```
>> gp1=tf(1,poly([0 -1 -2]))  
  
Transfer function:  
1  
-----  
s^3 + 3 s^2 + 2 s  
  
>> gp2=tf(poly([-0.8-3*i -0.8+3*i]),poly([-0.8-3*i -0.8+3*i]))  
  
Transfer function:  
s^2 + 1.6 s + 9.64  
-----  
s^2 + 1.6 s + 9.64  
  
>> gp2=tf(poly([-2-5*i -2+5*i]),poly([-0.8-3*i -0.8+3*i]))  
  
Transfer function:  
s^2 + 4 s + 29  
-----  
s^2 + 1.6 s + 9.64  
  
>> g=gp1*gp2  
  
Transfer function:  
s^2 + 4 s + 29  
-----  
s^5 + 4.6 s^4 + 16.44 s^3 + 32.12 s^2 + 19.28 s
```

Using Matlab:

```
>> rlocus(G)
```



**Figure 9 Root locus produced using rlocus(.)**

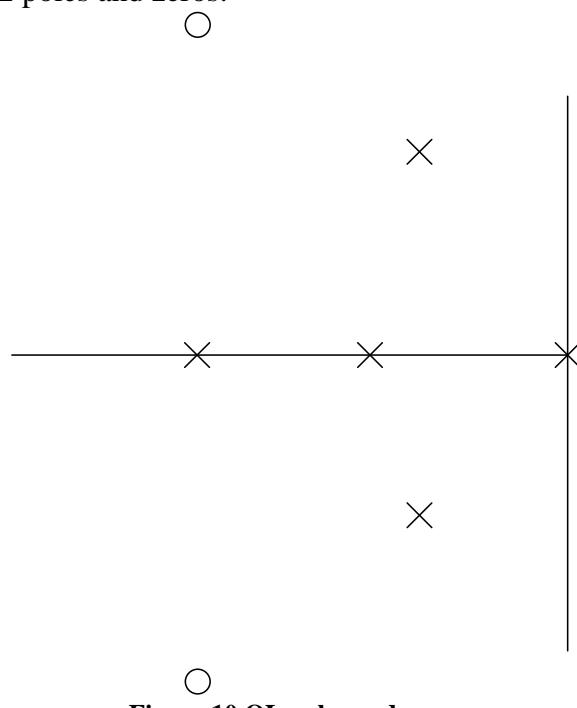
The graphical method:

The open loops poles are obviously 0, -1 , -2 from the 1<sup>st</sup> TF and  $-0.8 \pm 3j$  from the 2<sup>nd</sup> TF. The zeros are  $-2 \pm 5j$  but it can also be found using Matlab:

```
>> [p,z]=pzmap(G)
>> [p,z]=pzmap(g)
p =
0
-0.80000000000000 + 3.00000000000000i
-0.80000000000000 - 3.00000000000000i
-2.00000000000001
-1.00000000000000
z =
-2.00000000000000 + 5.00000000000000i
-2.00000000000000 - 5.00000000000000i
```

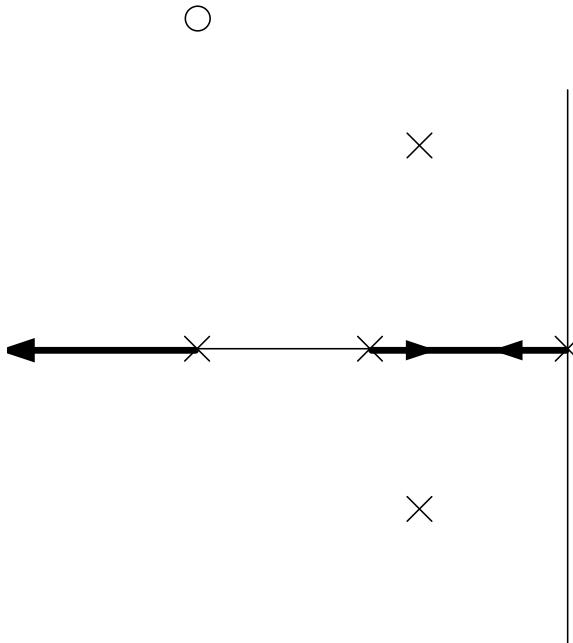
Note: The steps shown here are at a different sequence than those presented in your handout (chapter 4, last page).

**Step 1:** Draw the OL poles and zeros:



**Figure 10** OL poles and zeros

**Step 2:** Determine which parts of the real axis belong to the RL:



**Figure 11 Real axis part**

**Step 3:** The Break in/out points can be found from  $\frac{dk}{ds} = 0$  where  $k(s)$  is found using

$$\text{the CL CE: } k = \frac{-s(s+1)(s+2)(s+0.8+3j)(s+0.8-3j)}{(s+2+5j)(s+2-5j)}$$

(note: try to clearly understand the following steps)

```

>> [n, d]=tfdata(g, 'v')
dd=[5*d(1) 4*d(2) 3*d(3) 2*d(4) d(5)]
nd=[5*d(1) 4*d(2) 3*d(3) 2*d(4) d(5)]

roots(conv(dd,n)-conv(d,nd))
n =
      0      0      0      1      4     29
d =
  Columns 1 through 4
    1.00000000000000    4.60000000000000   16.44000000000000
32.12000000000001
  Columns 5 through 6
    19.28000000000000          0
dd =
  Columns 1 through 4
    5.00000000000000   18.40000000000000   49.32000000000001
64.24000000000001
  Column 5
    19.28000000000000
nd =
  Columns 1 through 4
    5.00000000000000   18.40000000000000   49.32000000000001
64.24000000000001
  Column 5
    19.28000000000000
ans =
-0.72486921028210 + 3.06190964590823i
-0.72486921028210 - 3.06190964590823i
-0.83563600935911 + 2.26917322324497i

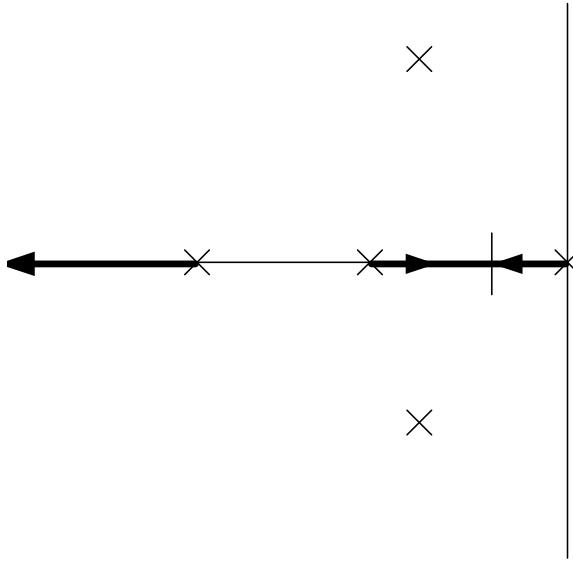
```

```

-0.83563600935911 - 2.26917322324497i
-1.90295033612183 + 0.91994346786326i
-1.90295033612183 - 0.91994346786326i
-1.59539068314997
 0.65563909280787
-0.41333729813182

```

Hence the accepted solution (break out point) is -0.41 (use your mouse pointer on the Matlab figure to crosscheck your answer).



**Figure 12 Break out point**

**Step 4:** There are  $n_p - n_z = 5 - 2 = 3$  asymptotes and the point of intersection with the real axis:

$$s = -\frac{\sum_{i=1}^{n_p} p_i - \sum_{i=1}^{n_z} z_i}{n_p - n_z}$$

```

>> pj=-p
pj =
          0
 0.800000000000000 - 3.00000000000000i
 0.800000000000000 + 3.00000000000000i
 2.000000000000001
 1.000000000000000
>> zj=-z
zj =
 2.000000000000000 - 5.00000000000000i
 2.000000000000000 + 5.00000000000000i
>> -sum(pj)/sum(pi)
ans =
 -1.46422547644544

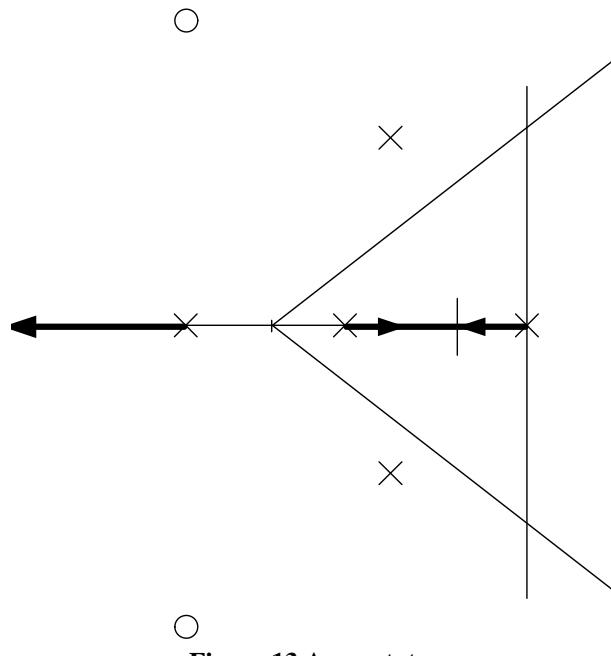
```

Hence  $s = -1.46$

The angles of the asymptotes with the real axis are:

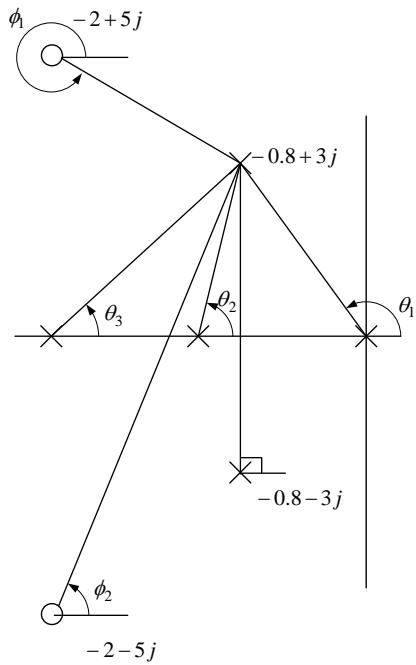
# asymptote	Angle
1	$180^\circ / 3 = 60^\circ$
2	$3 \times 180^\circ / 3 = 180^\circ$
3	$5 \times 180^\circ / 3 = 300^\circ$ or $-60^\circ$

The last 2 can also be found using the symmetry of the RL.



**Figure 13 Asymptotes**

**Step 5:** The angle of departure from the complex poles is found using the following drawing:



**Figure 14 Calculation of departure angle**

$$\theta_3 = \tan^{-1}\left(\frac{3}{1.2}\right) = 68.2^\circ$$

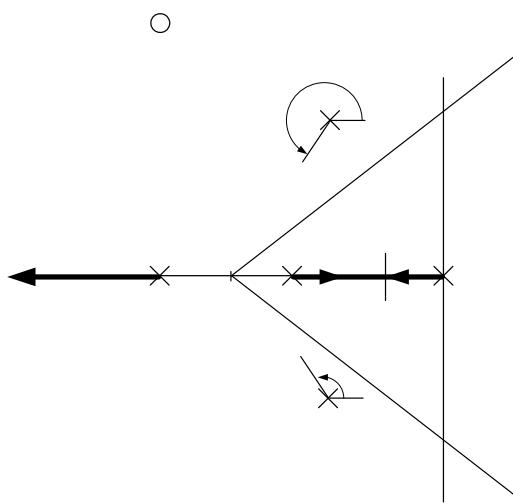
$$\theta_2 = \tan^{-1}\left(\frac{3}{0.2}\right) = 86.2^\circ$$

$$\tan^{-1}\left(\frac{3}{0.8}\right) = 75^\circ \Rightarrow \theta_2 = 180^\circ - 75^\circ = 105^\circ$$

$$\phi_2 = \tan^{-1}\left(\frac{3+5}{1.2}\right) = 81.5^\circ$$

$$\tan^{-1}\left(\frac{5-3}{1.2}\right) = 59^\circ \Rightarrow \phi_1 = 270 + 59 = 329$$

So the angle of departure is  $180^\circ - 68.2^\circ - 86.2^\circ - 105^\circ - 90^\circ + 81.5 + 329 = 241^\circ$



**Figure 15 Angle of departure**

**Step 6:** Angle of arrival at complex zero:

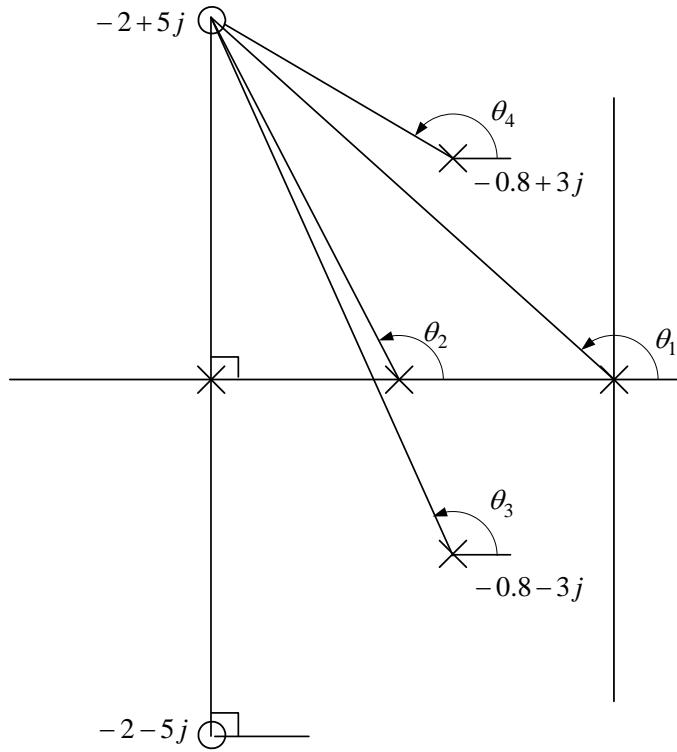


Figure 16

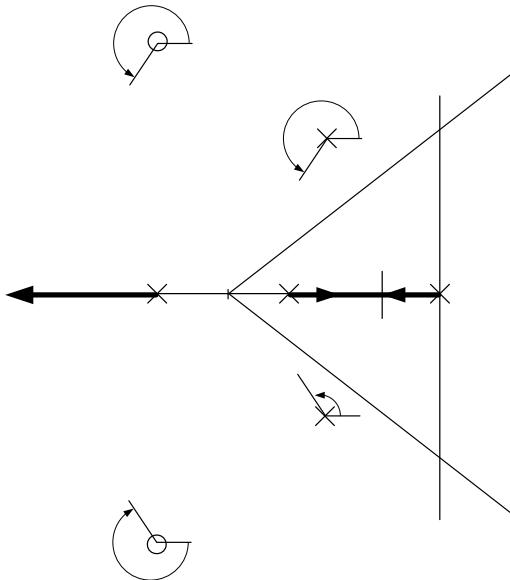
$$\tan^{-1}\left(\frac{5-3}{1.2}\right) = 59^\circ \Rightarrow \theta_4 = 180 - 59 = 121^\circ$$

$$\tan^{-1}\left(\frac{5+3}{1.2}\right) = 81.5^\circ \Rightarrow \theta_3 = 98.5^\circ$$

$$\tan^{-1}\left(\frac{5}{1}\right) = 78.7^\circ \Rightarrow \theta_2 = 101.3^\circ$$

$$\tan^{-1}\left(\frac{5}{2}\right) = 68.2^\circ \Rightarrow \theta_1 = 111.8^\circ$$

$$180^\circ - 90^\circ + 90^\circ + 121^\circ + 98.5^\circ + 101.3^\circ + 111.8^\circ = 612.6^\circ \text{ or } 252.6^\circ$$



**Figure 17 Angle of arrival**

**Step 7:** The last point is the point of intersection with the imaginary axis. To do that we place at the CL CE  $s=j\omega$ :

$$\begin{aligned}
 s^5 + 4.6 s^4 + 16.44 s^3 + 32.12 s^2 + 19.28 s + K(s^2 + 4s + 29) &= 0 \Leftrightarrow \\
 j\omega^5 + 4.6 \omega^4 - 16.44 j\omega^3 - 32.12 \omega^2 + 19.28 j\omega + K(-\omega^2 + 4j\omega + 29) &= 0 \Leftrightarrow \\
 j\omega^5 + 4.6 \omega^4 - 16.44 j\omega^3 - 32.12 \omega^2 + 19.28 j\omega - K\omega^2 + 4Kj\omega + 29K &= 0 \Rightarrow \\
 \left\{ \begin{array}{l} \omega^5 - 16.44\omega^3 + 19.28\omega + 4K\omega = 0 \\ 4.6\omega^4 - 32.12\omega^2 - K\omega^2 + 29K = 0 \end{array} \right\} &\Rightarrow \\
 \left\{ \begin{array}{l} \omega^4 - 16.44\omega^2 + 19.28 + 4K = 0 \\ 4.6\omega^4 - 32.12\omega^2 - K\omega^2 + 29K = 0 \end{array} \right\} &\Rightarrow
 \end{aligned}$$

To solve that I will use the command `solve(.)`

```

>> f=solve('w^4-16.44*w^2+19.28+4*k','4.6*w^4-32.12*w^2-w^2*k+29*k')
f =
k: [6x1 sym]
w: [6x1 sym]
>> f.k
ans =
1.5305102953532435416275289415472
1.5305102953532435416275289415472
48.066744852323378229186235529226+28.380111761239544420282550946110*i
48.066744852323378229186235529226+28.380111761239544420282550946110*i
48.066744852323378229186235529226-28.380111761239544420282550946110*i
48.066744852323378229186235529226-28.380111761239544420282550946110*i
>> f.w
ans =
-1.3139395436854506015568077305538
1.3139395436854506015568077305538
-3.9148964819517940077720670409119+1.6339011679500992572044216409525*i
3.9148964819517940077720670409119-1.6339011679500992572044216409525*i
-3.9148964819517940077720670409119-1.6339011679500992572044216409525*i
3.9148964819517940077720670409119+1.6339011679500992572044216409525*i

```

Hence the gain in 1.53 and the point is 1.31 rad/s

Now we have all that we need to sketch the root locus:

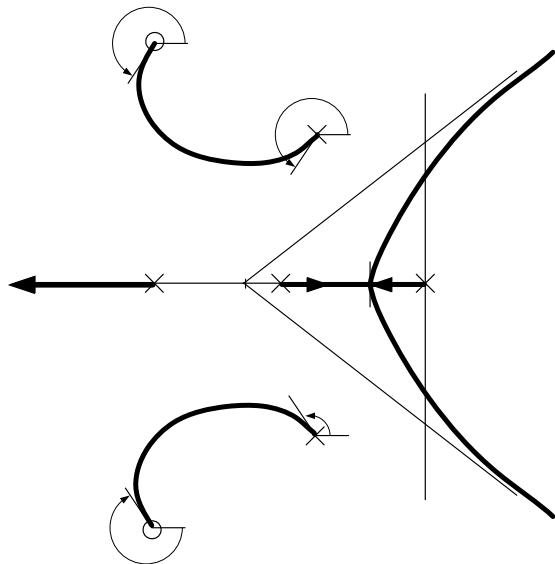


Figure 18

Further exercises

- 1) Repeat the original exercise but with  $G_{p2}(s) = (s + 2 + 5j)(s + 2 - 5j)$ .
- 2) Repeat the original exercise but with  $G_{p2}(s) = \frac{1}{(s + 0.5 + 0.3j)(s + 0.5 - 0.3j)}$ .
- 3) Repeat the original exercise but with  $G_{p2}(s) = \frac{(s + 1.3 + j)(s + 1.3 - j)}{(s + 0.8 + 3j)(s + 0.8 - 3j)}$ .

Note: it is EXTREMELY important that you do and fully UNDERSTAND these exercises.