

$$A = \begin{bmatrix} a & 0 \\ 0 & b \end{bmatrix}$$

2 L.I.

Revision

$$A = \begin{bmatrix} a & 1 \\ 0 & a \end{bmatrix}$$

1 L.I.

$$A = \begin{bmatrix} 0 & c \\ 0 & a \end{bmatrix}$$

2 L.I.

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$$A = \begin{bmatrix} a & b \\ -b & a \end{bmatrix}$$

2 L.I.

$e^{At} = \dots$

$$A = \begin{bmatrix} a & 0 & 0 & \dots \\ & a & & \\ & & a & \\ & & & \ddots \\ & & & & a \end{bmatrix}$$

$\rightarrow$  0s or 1s

# of zeros + 1 = L.I.

$$A = \begin{bmatrix} a & b & 0 & 0 \\ -b & a & 0 & 0 \\ 0 & 0 & a & b \\ 0 & 0 & -b & a \end{bmatrix}$$

$\rightarrow$  0

4 L.I.

$$A = \begin{bmatrix} a & b & 1 & 0 \\ -b & a & 0 & 1 \\ 0 & 0 & a & b \\ 0 & 0 & -b & a \end{bmatrix}$$

$\rightarrow$  1

2 L.I.

$$\begin{cases} \dot{x} = Ax + Bu \\ y = Cx \end{cases} \xrightarrow{x = T \cdot z} \begin{cases} \dot{z} = \hat{A} \cdot z + \hat{B} \cdot u \\ y = \hat{C} \cdot z \end{cases} \quad (38)$$

Better

$$T = \text{constant}$$

$$T = \text{inv}$$

eigenvalues = same  
NOT eigenvectors

$$\hat{A} = T^{-1} \cdot A \cdot T$$

$$\hat{B} = T^{-1} \cdot B$$

$$\hat{C} = C \cdot T$$

$$Gx = Gz$$

$$e^{\hat{A}t} = \text{easy} \rightarrow e^{AT} = T e^{\hat{A}t} T^{-1}$$

A

•  $\lambda_1 = a, \lambda_2 = b, \lambda_1 \neq \lambda_2$ , Target  $\hat{A} = \begin{bmatrix} a & 0 \\ 0 & b \end{bmatrix}$

•  $\lambda_1 = a = \lambda_2$ ,  
 $e_1, L.J.$

Target  $\hat{A} = \begin{bmatrix} a & \phi \\ 0 & a \end{bmatrix}$

•  $\lambda_1 = \lambda_2 = a$   
 $e_1, R_2 L.J.$

Target  $\hat{A} = \begin{bmatrix} a & 0 \\ 0 & a \end{bmatrix}$

•  $\lambda = a \pm bi$

Target  $\hat{A} = \begin{bmatrix} a & b \\ -b & a \end{bmatrix}$

I know, A,  $\hat{A}$ ,  $T = ?$

$$\hat{A} = T^{-1} \cdot A \cdot T$$

I want to find a T :

$$T \cdot \hat{A} = A T$$

known

~~$\lambda_1 \neq \lambda_2$~~   
 ~~$a \neq b$~~   
 $e_1, e_2$  L.I.

$$\hat{A} = \begin{bmatrix} a & 0 \\ 0 & b \end{bmatrix}$$

$$(A - \lambda I)e = 0$$

$$A \cdot e = \lambda \cdot e$$

$$A \cdot e_1 = \lambda_1 e_1$$

$$A \cdot e_2 = \lambda_2 e_2$$

$$\left. \begin{array}{l} A \cdot e_1 = \lambda_1 e_1 \\ A \cdot e_2 = \lambda_2 e_2 \end{array} \right\} \Rightarrow A [e_1 \ e_2] = [e_1 \ e_2] \begin{bmatrix} \lambda_1 & 0 \\ 0 & \lambda_2 \end{bmatrix}$$

known

$2 \times 2$

$2 \times 1$       $2 \times 1$

$$A = \dots$$

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$$\lambda_1 = \lambda_2 \rightarrow e$$

$$\text{Target } \hat{A} = \begin{bmatrix} \alpha & 1 \\ 0 & \alpha \end{bmatrix}$$

$$A \cdot e = \lambda \cdot e + 0 \cdot b$$

$$e = (A - \lambda I) b$$

$$= A b - \lambda b$$

$$A b = e + \lambda b$$

$$\begin{aligned} & \rightarrow A \cdot \begin{bmatrix} e & b \end{bmatrix} \\ & = \begin{bmatrix} e & b \end{bmatrix} \cdot \begin{bmatrix} \lambda & 1 \\ 0 & \lambda \end{bmatrix} \end{aligned}$$

$$A = \dots \quad \lambda = a + bi \\ e = [v + wi]$$

$$\lambda, a, b \in \mathbb{R} \\ e, v, w \in \mathbb{R}^{n \times 1}$$

$$\hat{A} = \begin{bmatrix} a & b \\ -b & a \end{bmatrix}$$

$$\begin{aligned} a + bi &= c + di \\ a = c & \\ b = d & \end{aligned}$$

$$A \cdot e = \lambda \cdot e$$

$$A \cdot [v + wi] = (a + bi) \cdot (v + wi)$$

$$\begin{aligned} Av + Aw i &= a \cdot v + a w i + b i v - b w \\ &= a \cdot v - b w + (a w + b v) \cdot i \end{aligned}$$

$$Av = a v - b w$$

$$Aw = a w + b v$$



$$A \cdot [v \ w] = [v \ w] \cdot \begin{bmatrix} a & b \\ -b & a \end{bmatrix}$$

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# Vector space

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A set of objects that satisfy some rules.

$$\square + \square = \square$$

a subset of this set  $\rightarrow$  Basis  
L.C. can describe all other elements

$V = \{ \text{all 2nd order polynomials} \}$

$$v_1 = x^2 + x + 1$$

$$v_2 = 3x^2 + 5$$

$$v_3 = 3x - 2$$

$$v_1 + v_2 = 4 \cdot x^2 + x + 5 \in V$$

$$B_1 = \{ x^2, x, 1 \}$$

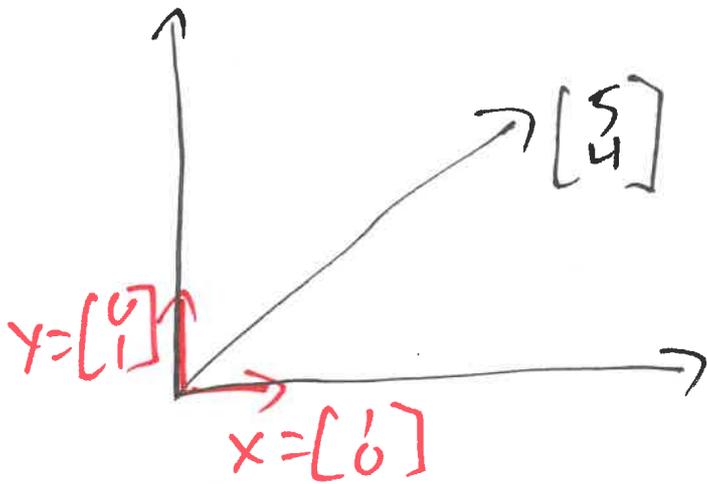
Basis

$$v_1 = 1 \cdot x^2 + 1 \cdot x + 1 \cdot 1$$

$$v_2 = 3 \cdot x^2 + 0 \cdot x + 5 \cdot 1$$

$$B_2 = \{3x^2, 5x, \sqrt{\pi} \cdot 1\}$$

(4/3)



$$B_1 = \left\{ \begin{bmatrix} 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \end{bmatrix} \right\}$$

$$\begin{bmatrix} 5 \\ 4 \end{bmatrix} = 5 \cdot \begin{bmatrix} 1 \\ 0 \end{bmatrix} + 4 \cdot \begin{bmatrix} 0 \\ 1 \end{bmatrix}$$

$$B_2 = \left\{ \begin{bmatrix} 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 2 \end{bmatrix} \right\}$$

$$\begin{bmatrix} 5 \\ 4 \end{bmatrix} = 5 \cdot \begin{bmatrix} 1 \\ 0 \end{bmatrix} + 2 \cdot \begin{bmatrix} 0 \\ 2 \end{bmatrix}$$

$$B_3 = \left\{ \begin{bmatrix} 1 \\ 3 \end{bmatrix}, \begin{bmatrix} 5 \\ 2 \end{bmatrix} \right\}$$

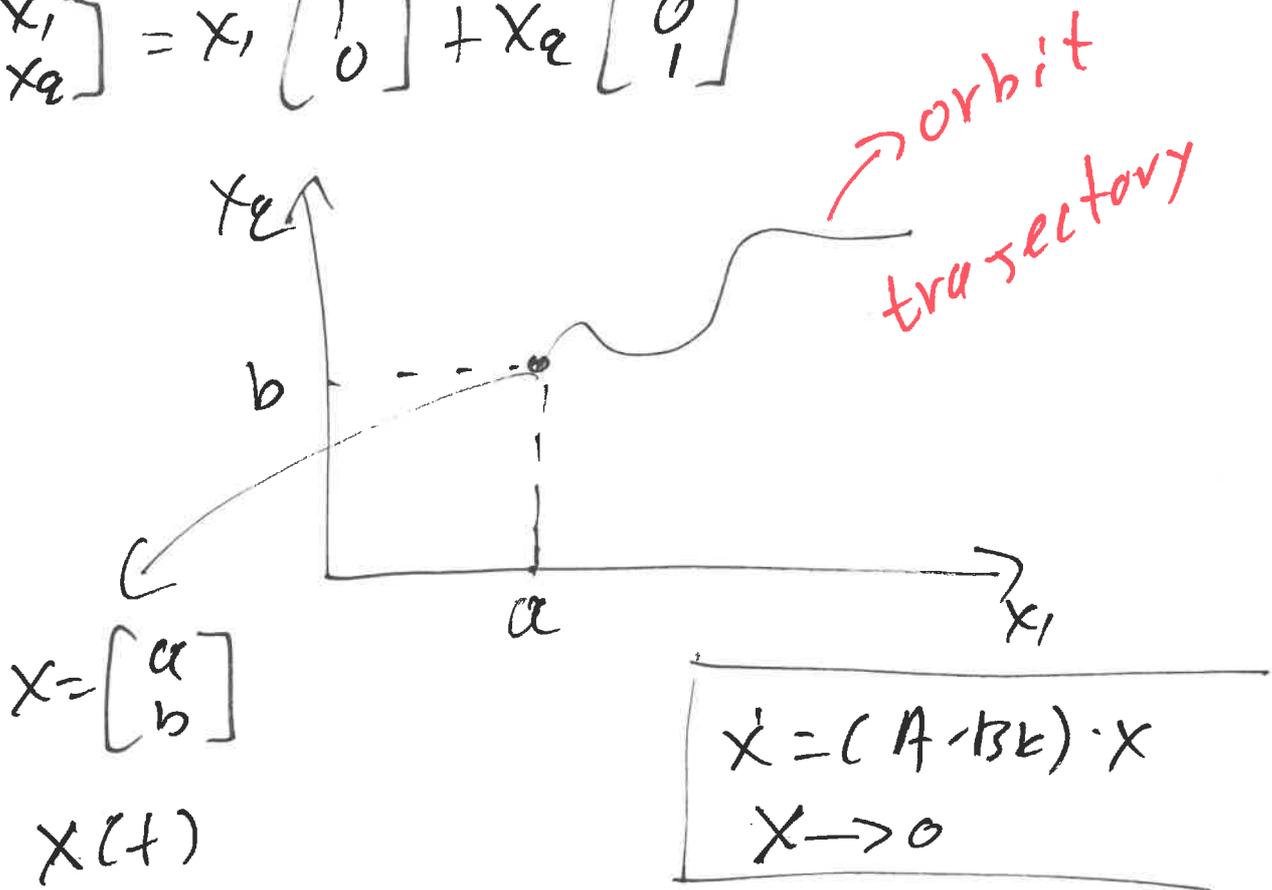
$$\begin{bmatrix} 5 \\ 4 \end{bmatrix} = a \cdot \begin{bmatrix} 1 \\ 3 \end{bmatrix} + b \cdot \begin{bmatrix} 5 \\ 2 \end{bmatrix} \Rightarrow$$

$$\left. \begin{array}{l} 5 = a \cdot 1 + b \cdot 5 \\ 4 = 3 \cdot a + 2b \end{array} \right\} \Rightarrow \dots$$

# State Space

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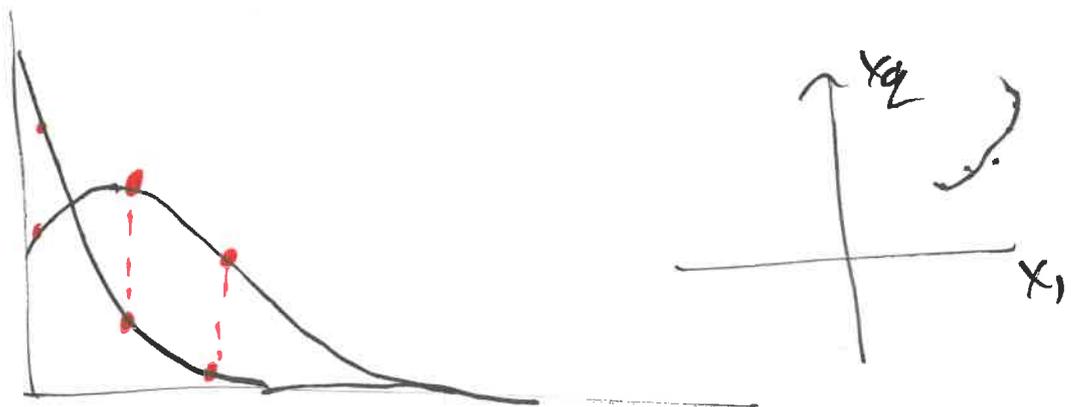
$$X = \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = x_1 \begin{bmatrix} 1 \\ 0 \end{bmatrix} + x_2 \begin{bmatrix} 0 \\ 1 \end{bmatrix}$$



$$\dot{X} = AX, \quad A = \begin{bmatrix} -2 & 2 \\ 2 & -5 \end{bmatrix}$$

$\rightarrow \lambda_1 = 1, \quad e_1 = \begin{bmatrix} 2 \\ 1 \end{bmatrix}$

$\rightarrow \lambda_2 = -6, \quad e_2 = \begin{bmatrix} 1 \\ -2 \end{bmatrix}$

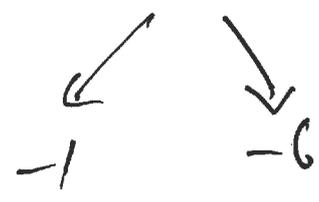


+ Matlab

$$A = \begin{bmatrix} -2 & 2 \\ 2 & -5 \end{bmatrix}$$

$$\dot{x} = A \cdot x$$

$$x = \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = x_1 \begin{bmatrix} 1 \\ 0 \end{bmatrix} + x_2 \begin{bmatrix} 0 \\ 1 \end{bmatrix}$$



$$\begin{bmatrix} 2 \\ 1 \end{bmatrix} \quad \begin{bmatrix} 1 \\ -2 \end{bmatrix}$$

$$x = \underbrace{c_1 \cdot e^{-t}}_{a(t)} \cdot \begin{bmatrix} 2 \\ 1 \end{bmatrix} + \underbrace{c_2 \cdot e^{-6t}}_{b(t)} \cdot \begin{bmatrix} 1 \\ -2 \end{bmatrix}$$

$$x = a \cdot \begin{bmatrix} 2 \\ 1 \end{bmatrix} + b \cdot \begin{bmatrix} 1 \\ -2 \end{bmatrix}$$

x given as a L.C. of eigenvector.



Form  
eigenbasis

$$X = C_1 \cdot e^{-t} \begin{bmatrix} 2 \\ 1 \end{bmatrix} + C_2 \cdot e^{-6t} \begin{bmatrix} 1 \\ -2 \end{bmatrix} \quad 46.$$

$$X_0 = \begin{bmatrix} 1 \\ 1 \end{bmatrix} \Rightarrow \dots \quad C_1 = \dots$$

$$X_0 = 3 \cdot e_1 = \begin{bmatrix} 3 \\ 0 \end{bmatrix}$$

$$C_1 \begin{bmatrix} 2 \\ 1 \end{bmatrix} + C_2 \begin{bmatrix} 1 \\ -2 \end{bmatrix} = k \cdot e_1$$

$$C_1 = k$$

$$C_2 = 0$$

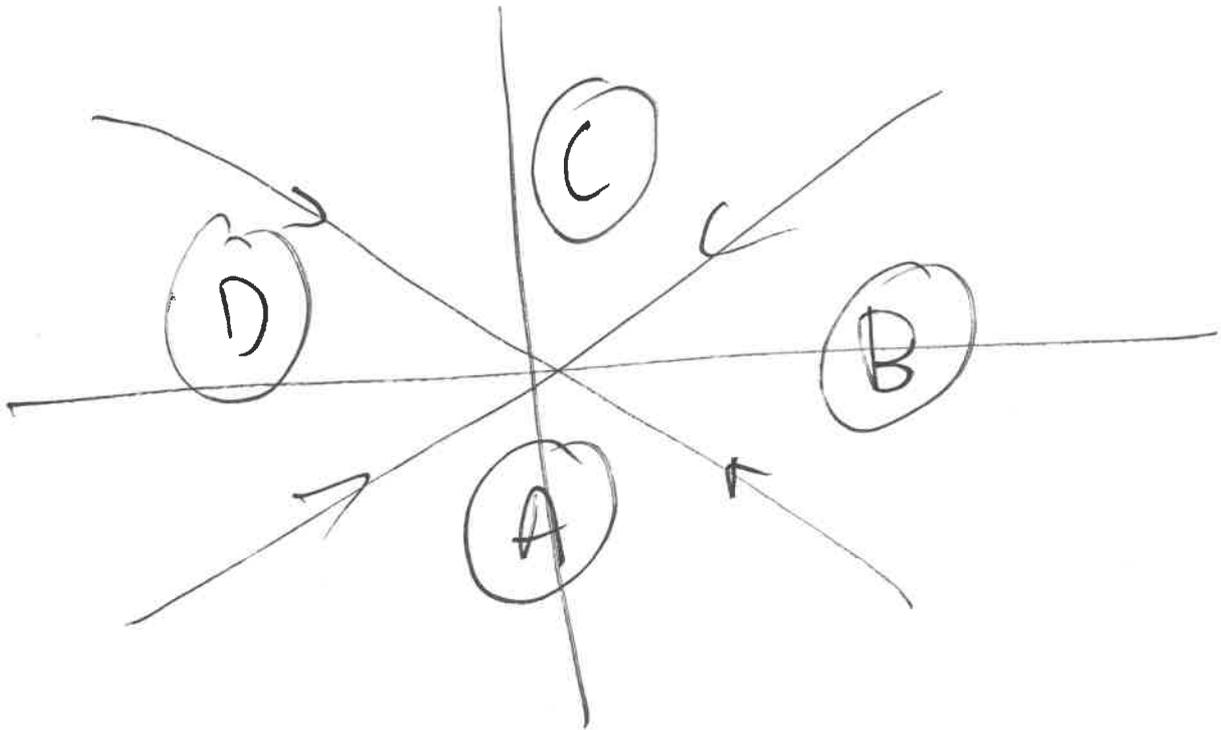
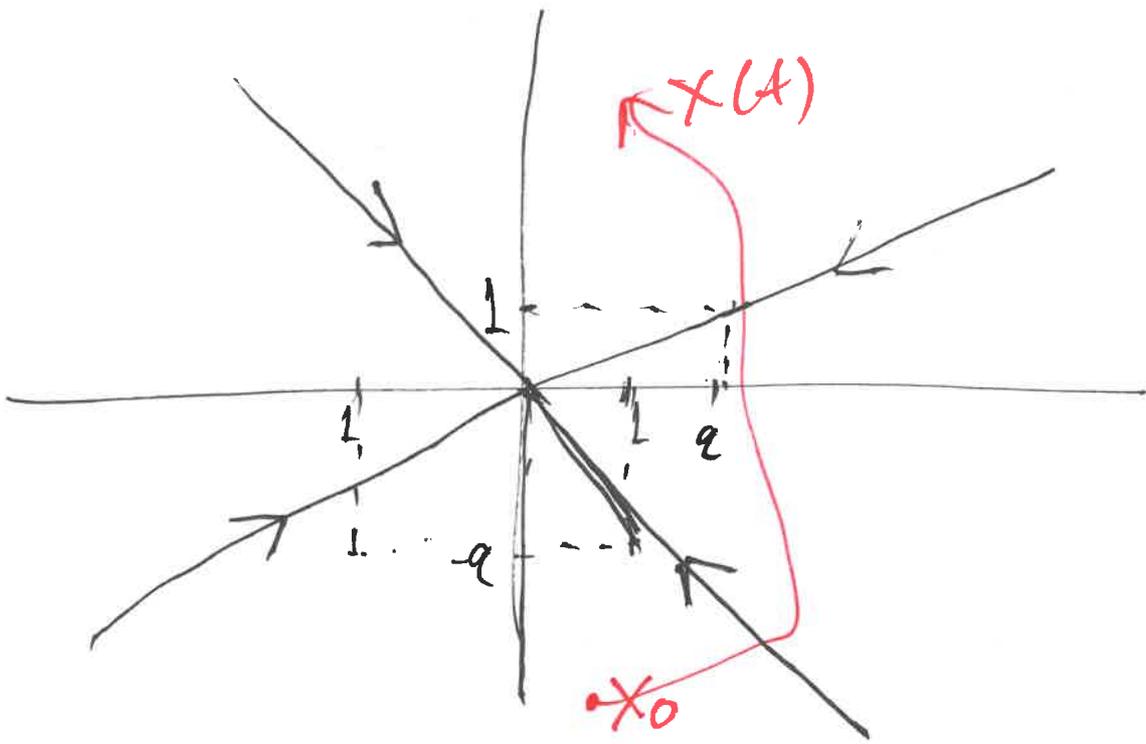
$$X = k \cdot e^{-t} \begin{bmatrix} 2 \\ 1 \end{bmatrix}$$

$$\text{if } X_5 = 20 \cdot e_1 = C_1 \cdot e^{-5} \begin{bmatrix} 2 \\ 1 \end{bmatrix} + C_2 \cdot e^{-30} \begin{bmatrix} 1 \\ -2 \end{bmatrix}$$

$$C_2 = 0$$

if at  $t=t$ , you are on  $e_1$  (or  $e_2$ )  
 then ~~you~~ you will stay on  $e_1$  forever  
 (or  $e_2$ )

$e_1$  (or  $e_2$ ) is invariant  
 under time



$$A = \dots \quad e_1 = \begin{bmatrix} 2 & 1 \end{bmatrix}^T \quad \lambda_1 = -1$$

$$e_2 = \begin{bmatrix} 1 & -2 \end{bmatrix}^T \quad \lambda_2 = -6$$

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$$X = c_1 e^{-t} \begin{bmatrix} 2 \\ 1 \end{bmatrix} + c_2 e^{-6t} \begin{bmatrix} 1 \\ -2 \end{bmatrix}$$