

Revision

$$\begin{aligned} \dot{x} &= Ax + Bu \\ y &= Cx + Du \end{aligned} \quad \left\{ \begin{array}{l} x = Tz \\ T = \text{inv} \end{array} \right. \quad \begin{array}{l} z = T^{-1}x \\ \downarrow A \end{array} \quad \begin{array}{l} \dot{z} = T^{-1}AT \cdot z + T^{-1}B \cdot u \\ \downarrow B \end{array}$$

$$z = T^{-1}x \quad y = \underbrace{C \cdot T \cdot z}_{\downarrow C} + \underbrace{D \cdot u}_{\downarrow D}$$

Both models \rightarrow same T.F.

\rightarrow same CTRB/OBSV

$$e^{At} = T e^{\hat{A}t} T^{-1} \quad \text{or} \quad e^{\hat{A}t} = \underline{T^{-1} e^{At} \cdot T}$$

If T eigenmatrix

Assume $n=2$

- $T = [\ell_1 \quad \ell_2] \quad \cdot T = [e \quad b] \quad \cdot T = [Re(e) \quad I_n(e)]$
- \downarrow gen eig

$\square T = [\ell_1 \quad \ell_2] \rightarrow \hat{A} = \begin{bmatrix} \lambda_1 & 0 \\ 0 & \lambda_2 \end{bmatrix} \rightarrow \hat{\ell}_1 = [1 \quad 0]^T$

\downarrow

$\hat{\ell}_2 = [0 \quad 1]^T$

$\Rightarrow e^{\hat{A}t} = \begin{bmatrix} e^{\lambda_1 t} & 0 \\ 0 & e^{\lambda_2 t} \end{bmatrix}$

$$\lambda_1 = \alpha + bi, \lambda_2 = \bar{\lambda}_1, \alpha, b \in \mathbb{R}$$

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$$e_1 = [v + wi], e_2 = \bar{e}_1, v, w \in \mathbb{R}^{n \times 1}$$

$$e_1, e_2 \in \mathbb{C}^{n \times 1}$$

assume $n=2$

$$A \cdot e_1 = \lambda_1 e_1 \Leftrightarrow$$

$$A \cdot [v + wi] = (\alpha + bi) \cdot [v + wi].$$

$$= \alpha v + \alpha wi + b \cdot vi - bw i \\ = (\alpha v - bw) + (\alpha w + b v) \cdot i \Rightarrow$$

$$Av + A \cdot wi$$

$$\left. \begin{array}{l} Av = \alpha v - bw \\ Aw = \alpha w + bv \end{array} \right\} \Rightarrow A \cdot [v \ w] = [v \ w] \cdot \begin{bmatrix} \alpha & b \\ -b & \alpha \end{bmatrix}$$

$$A \cdot T = T \cdot \hat{A}$$

$$A = T \cdot \hat{A} \cdot T^{-1}$$

$$e_1 = [1 \ i]^T$$

$$\hat{A} = \begin{bmatrix} \operatorname{Re}(\lambda) & \operatorname{Im}(\lambda) \\ -\operatorname{Im}(\lambda) & \operatorname{Re}(\lambda) \end{bmatrix}$$

$$e_2 = [1 \ -i]^T$$

$$e^{\hat{A}t} = e^{\alpha t} \begin{bmatrix} \cos bt & \sin bt \\ -\sin bt & \cos bt \end{bmatrix}$$

$$e^{At} = T e^{\hat{A}t} T^{-1}$$

• $\lambda = \lambda_1 = \lambda_2 \rightarrow \ell$, $b \rightarrow$ gen. eig.

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$$(A - \lambda I) \cdot \ell = 0 \quad \ell = (A - \lambda I)^{-1} \cdot b.$$

$$A\ell = \lambda \ell \quad \ell = A \cdot b - \lambda b$$

$$Ab = \ell + \lambda b.$$

$$A \cdot T = A \cdot [e \quad b] =$$

$$= [Ae \quad A \cdot b] \\ = [Ae \quad e + \lambda b]$$

$$= [\lambda e \quad e + \lambda b]$$

$$= [e \quad b] \cdot \begin{bmatrix} \lambda & 1 \\ 0 & \lambda \end{bmatrix}$$

$$= T \cdot \hat{A}$$

$$\hat{A} = T^{-1} A T$$

$$e^{\hat{A}t} = \begin{bmatrix} e^{\lambda t} & t e^{\lambda t} \\ 0 & e^{\lambda t} \end{bmatrix}$$

V.S.

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A set of objects (vectors)

$$V = \{v_1, v_2, \dots\}$$

1) If $v_1, v_2 \in V \Rightarrow v_1 + v_2 \in V$

2) if $v_1, v_2 \in V \Rightarrow v_1 + v_2 = v_2 + v_1 \in V$

3) $\exists 0: 0 + v_1 = v_1 + 0$

e.g. $V = \{x^2, 3x^2, 3.1x^2, -x^2, \dots\}$

$$= \{\alpha \cdot x^2\} \quad \alpha \in \mathbb{R}$$

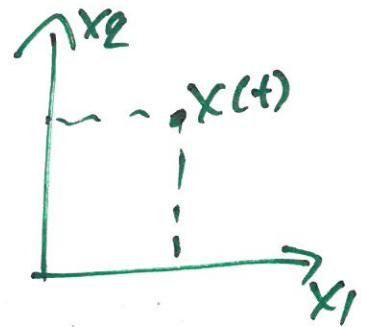
$$\dot{x} = \begin{bmatrix} -2 & 2 \\ 2 & -5 \end{bmatrix} \cdot x$$

Q3

$$x = \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = x_1 \begin{bmatrix} 1 \\ 0 \end{bmatrix} + x_2 \begin{bmatrix} 0 \\ 1 \end{bmatrix}$$

$$\lambda_1 = -1 \rightarrow e_1 = \begin{bmatrix} 2 \\ 1 \end{bmatrix}$$

$$\lambda_2 = -6 \rightarrow e_2 = \begin{bmatrix} 1 \\ -2 \end{bmatrix}$$



$$\begin{aligned} x &= c_1 e_1 e^{\lambda_1 t} + c_2 e_2 e^{\lambda_2 t} \\ &= c_1 e^{-t} \cdot \begin{bmatrix} 2 \\ 1 \end{bmatrix} + c_2 e^{-6t} \cdot \begin{bmatrix} 1 \\ -2 \end{bmatrix} \\ &= \alpha(t) \cdot \begin{bmatrix} 2 \\ 1 \end{bmatrix} + b(t) \cdot \begin{bmatrix} 1 \\ -2 \end{bmatrix} \end{aligned}$$

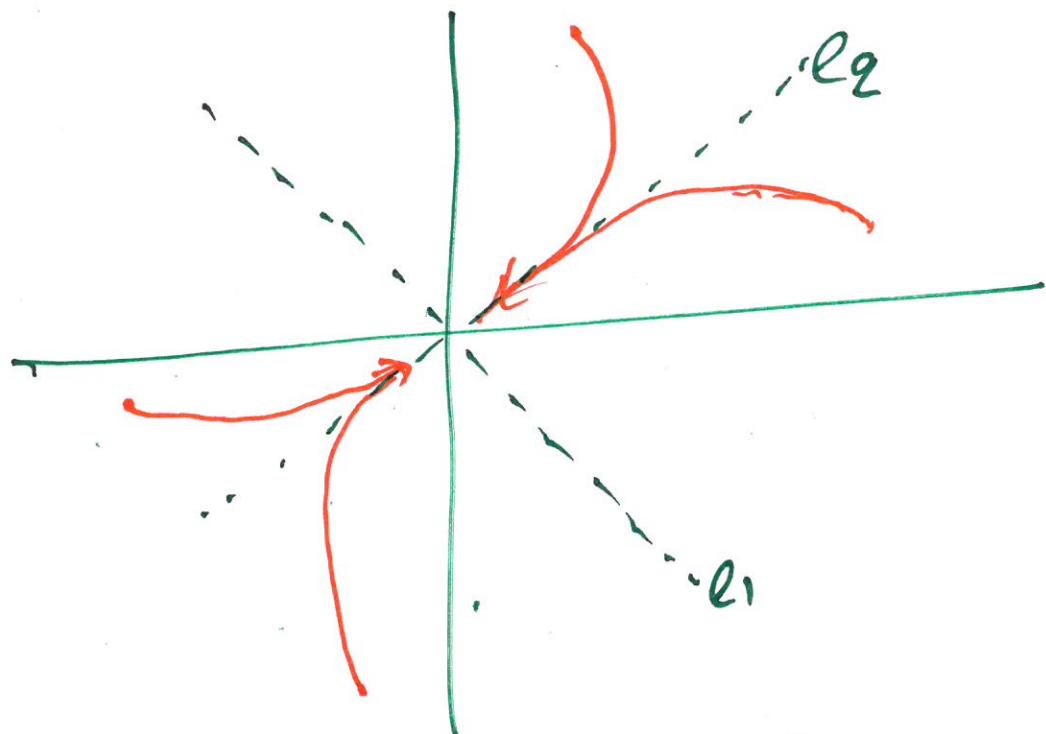
new basis

$$\dot{x} = \begin{bmatrix} -5.5 & 45 \\ 45 & -5.5 \end{bmatrix} x$$

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$$\tau_1 = -10 \quad e_1 = \begin{bmatrix} -1 & 1 \end{bmatrix}$$

$$\lambda_2 = -1 \quad e_2 = \begin{bmatrix} 1 & 1 \end{bmatrix}$$



$$x = c_1 \begin{bmatrix} -1 \\ 1 \end{bmatrix} e^{-10t} + c_2 \begin{bmatrix} 1 \\ 1 \end{bmatrix} e^{-t}$$

$$\text{very fast} \quad x \approx c_2 e^{-t} \cdot \begin{bmatrix} 1 \\ 1 \end{bmatrix}$$

$$= a(t) \begin{bmatrix} 1 \\ 1 \end{bmatrix}$$

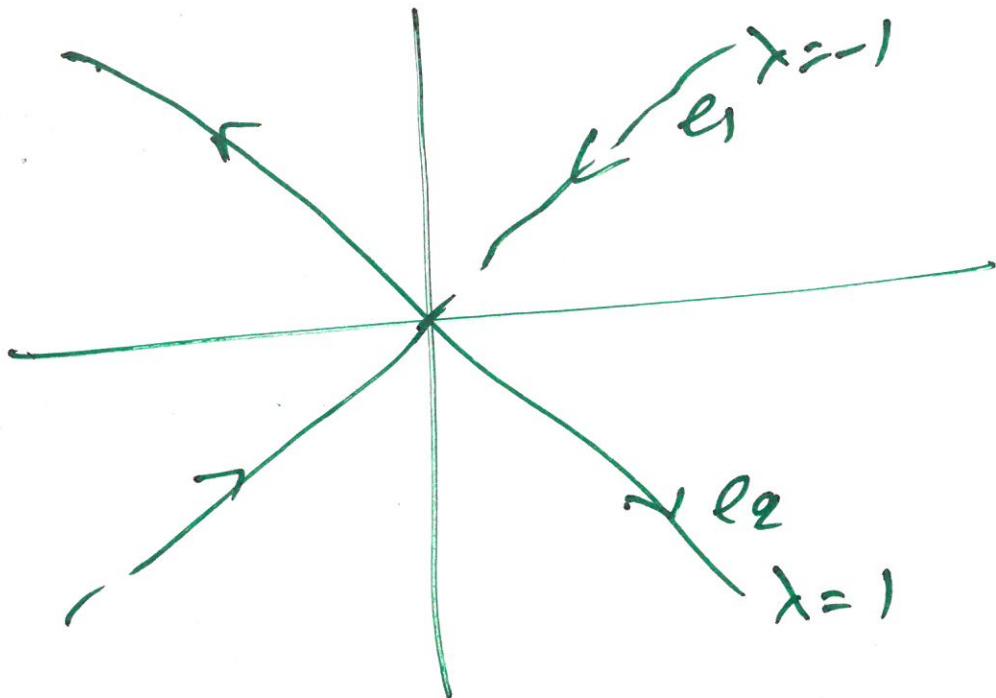
$$\text{I.Q. } x = a(t) \cdot \begin{bmatrix} -1 \\ 1 \end{bmatrix} + b(t) \cdot \begin{bmatrix} 1 \\ 1 \end{bmatrix}$$

$$\text{Assume that at } t=t_1 \quad x = b(t_1) \cdot \begin{bmatrix} 1 \\ 1 \end{bmatrix}$$

$$\text{i.e. } a(t_1) = 0$$

$$c_1 e^{-t_1} = 0 \Rightarrow c_1 = 0$$

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$$x = c_1 e^{-t} \cdot l_1 + c_2 e^{+t} \cdot l_2$$

If $x_0 : c_1, c_2 \neq 0$

If $x_0 : c_1 \neq 0, c_2 = 0$